



LPMS

- linear PiezoMotor driven system
- Travel range is 15 to 70 mm
- Bidirectional repeatility down to 20nm
- Maximum operation speed 10mm/sec
- Intergeated zerodrift encoder with 10 nm resolution
- Force 10N/ 20N
- High stiffness and fast response.
- Material Stainless steel,
- Vacuum compatibe
- flexible cable
- guiding is a ballbearing from 3 sites

This is a micrometer screw replacement. It works direct linear (without screw) is a cusomized PiezoMotor with integreated magnetic encoder and a simple ballbering guiding for the rod. The mounting Adapter has 9,5mm diameter together with a 3/8 "-40 UNS tread. For more force a tandem motor is possible. For a resolution down to 5 nm is a double magnetic encoder is possible.

| LPMS | | | |
|--|--------------|-------------|---------------------------------|
| dimension mm | 10.8*19*33.5 | 12*25*33.5 | 10.8*19*56 |
| | dimensions | dimensions | dimensions |
| | without rod | without rod | without rod |
| Rod L (mm) | 50/70/100 | 50/70/100 | 70/100 |
| Travel range (mm) | 20/40/70 | 20/40/70 | 18/48 |
| Force (N) | 10 | 20 | 20 |
| Open loop stiffness (N/µm) | 3 | 3 | 6 |
| operation speed (mm/s) | 10 | 10 | 10 |
| fast movement** (mm/s) | 50 | 50 | 50 |
| Hybrid encoder V2 (nm) with ABZ, 18mA @ 5V *** | 61(10) | 61(10) | 61(10)/ |
| | | | 5nm with two encoders |
| Hybrid encoder V3 (nm) with ABZLL, 18mA @ 5V *** | 61(10) | 61(10) | 61(10) 5nm with two encoders |
| Hybrid encoder V4 (nm) with ABZ, 3mA @ 5V **** | 10 | 10 | 10 5nm with two encoders |
| Bidirectional Repeatability (Encodercounts) | 2 | 2 | 2 |

Specifications



** Fast movement is possible for a short time with the LEGS-Drive®-Ultra Controller *** take a looke to the datasheet Hybrid encoder V2, V3. 10nm Resolution is possible with the LEGS-Drive®-Ultra Controller **** take a looke the the datasheet Hybrid Encoder V4

Order code for this product:

LPMS -L-S-P-T-M-A

L = Lenth of rod $\frac{50}{70}$ mm is standard other are possible.

| S = Sensors | S0 1V2_61 V2_0 | without sensor for open loop application 61nm resolution(magnetic encoder) ABZ TTL Oversample function 10nm resolution (LEGS-Drive®-Ultra Controller or MC101: magnetic encoder) ABZ TTL | | |
|--------------|--|---|--|--|
| | 2V2_O | 10nm resolution (LEGS-Drive®-Ultra Controller; magnetic encoder) ABZ TTL (only wth tandem motor possible) | | |
| | 1V3_61; 1V3_0 | 61nm resolution(magnetic encoder) ABZ, 2 limit, Error TTL Oversample function 10nm resolution (LEGS-Drive®-Ultra Controller or MC101; magnetic encoder) ABZ, 2 limit, Error TTL | | |
| | 2V3_0 | 10nm resolution (LEGS-Drive®-Ultra Controller; magnetic encoder) ABZ, 2 limit, Error TTL. (only wth tandem motor possible) | | |
| | 1V4_10 | 10nm resolution (magnetic encoder) ABZ TTL | | |
| | 2V4_10 | 10nm resolution (magnetic encoder) ABZ TTL (only with tandem motor possible) | | |
| Р | 1 | one Piezomotor | | |
| | 2 | two motors in a twin system | | |
| | 3 | two motors in a tandem system | | |
| T = Tip | 0 | without (ceramic rod end) | | |
| | 1 | with Cuppling (aluminium part with sheet metal) | | |
| | 2 | with stainless steel ball | | |
| | 3 | with ceramic ball | | |
| M = Mountin | g | | | |
| | 0 | 2 m1,6 screw at the front site | | |
| | 1 | Ø 9,5h7 fitting and M9,5mm thread | | |
| A = atmosphe | ere | | | |
| - | N normal | | | |
| | V vacuum | | | |
| | HV High vacuum (please ask for force and life time) | | | |
| | UHV Ultra high Vacuum (please ask for force and life time) | | | |



So the order code could be for example: LPMS-50-1V4_10-1-2-1-N

--> so the Piezomotor has a 50mm drive rod (20mm stroke), 10N, the Encoder has10nm resolution, ABZ, and an error signa, the Drivrod with glued scale is guided, has a stainless steel ball and is for normal atmosphere. It has a micrometer screw interface.

Dimensions:





Stainless steel Nut

open loop with adapter



closed loop with adapter





Tandem version closed loop with adapter and double encoder



Twin version closed loop with adapter

Applications:





replace a 25mm micrometer screw and has 1000 times higher resolution (10nm) closed loop; 10 or 20N strong